# Robotic Product Ideas targeting Medical Applications in Diagnosis and Intervention

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### Requirements regarding Robotics in the OR

#### Industrial requirements:

- High Speed
  - -> High Accelerations
- High Payload Capacity
- High Accuracy
  - -> High Stiffness



#### OR requirements:

- Slim and sleek design
- Fail-safe actuation
- low speed, less accuracy
- Payload capacity ~ 5kg
- Active constraints in real-time
- redundant DOF







## Possible new robotic applications in the OR

1. Instrument-holding and guiding device with slim contours



2. intracorporal micro-kinematics







